2011 VLSI Circuits Short Course Program

"Device Awareness in Circuit Design"

Tuesday, June 14, 2011 (Suzaku I)

Organizers/Chairs: Masato Yoshioka, *FUJITSU LABORATORIES LTD.* Gunther Lehmann, *Infineon Technologies*

8:10	Introduction Masato Yoshioka, FUJITSU LABORATORIES LTD.
8:15	Random Variability: Measurements and Its Impact on SRAM Stability Toshiro Hiramoto, The Univ. of Tokyo
9:15	Noise from Scaled CMOS Device Tatsuya Ohguro, <i>Toshiba Corp.</i>
10:15	Break
10:30	Cause, Detection, and Impact of Charge Trapping on Aging Tibor Grasser, Vienna Univ. of Technology
11:30	Lunch
13:15	Technology Platform Selection and Its Impact on Design Parameters Been-Jon Woo, TSMC
14:15	Variation Monitoring and Management Systems for Low-power and Dependable LSIs Koichi Nose, <i>Renesas Electronics Corp.</i>
15:15	Break
15:30	Device Awareness in Fabless Mass Production - Digital Aspects Venugopal Puvvada, Qualcomm India Pvt Ltd.
16:30	Device Awareness in Fabless Mass Production - Analog/RF Hooman Darabi, <i>Broadcom Corp.</i>
17:30	Conclusion Gunther Lehmann, Infineon Technologies

(as of June 6, 2011)

2011 VLSI Circuits Workshop Program

"Bio Inspired Computation -What Electronics can learn from Bio-"

Tuesday, June 14, 2011 (Suzaku III)

Organizers/Chairs: Makoto Ikeda, *The Univ. of Tokyo* Michael P. Flynn, *Univ. of Michigan* Chen Yi Lee, *National Chiao Tung Univ.*

8:10	Introduction Makoto Ikeda, <i>The Univ. of Tokyo</i>
8:15	Cyborg Beetles: The Remote Radio Control of Insect Flight Michel M. Maharbiz, <i>Univ. of California, Berkeley</i>
9:15	Ultrasound Imaging using MEMS Sensor Array Shuntaro Machida, <i>Hitachi, Ltd.</i>
10:15	Break
10:30	Transitioning Neuromorphic Approaches from Science to Engineering Solutions Paul Hasler, <i>Georgia Tech</i>
11:30	Lunch
13:15	Bio-inspired Vision Tobi Delbruck, <i>Univ. of Zurich and ETH Zurich</i>
14:15	Cognitive Computing: From Neuroscience to Neural-Inspired Chips Paul A. Merolla, <i>IBM Corp.</i>
15:15	Break
15:30	Embedded Real-Time Processor for Massively Distributed Robot Control Nobuyuki Yamasaki, <i>Keio Univ.</i>
16:30	Conclusion Michael P. Flynn, <i>Univ. of Michigan</i>

(as of June 6, 2011)